

Robotic Production of Biomimetic Composites

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Rapid prototyping

Freeform fabrication

Multimaterial, multilayer fabrication

Rapid prototyping

Build a part directly from a 3D CAD drawing

Stereolithography

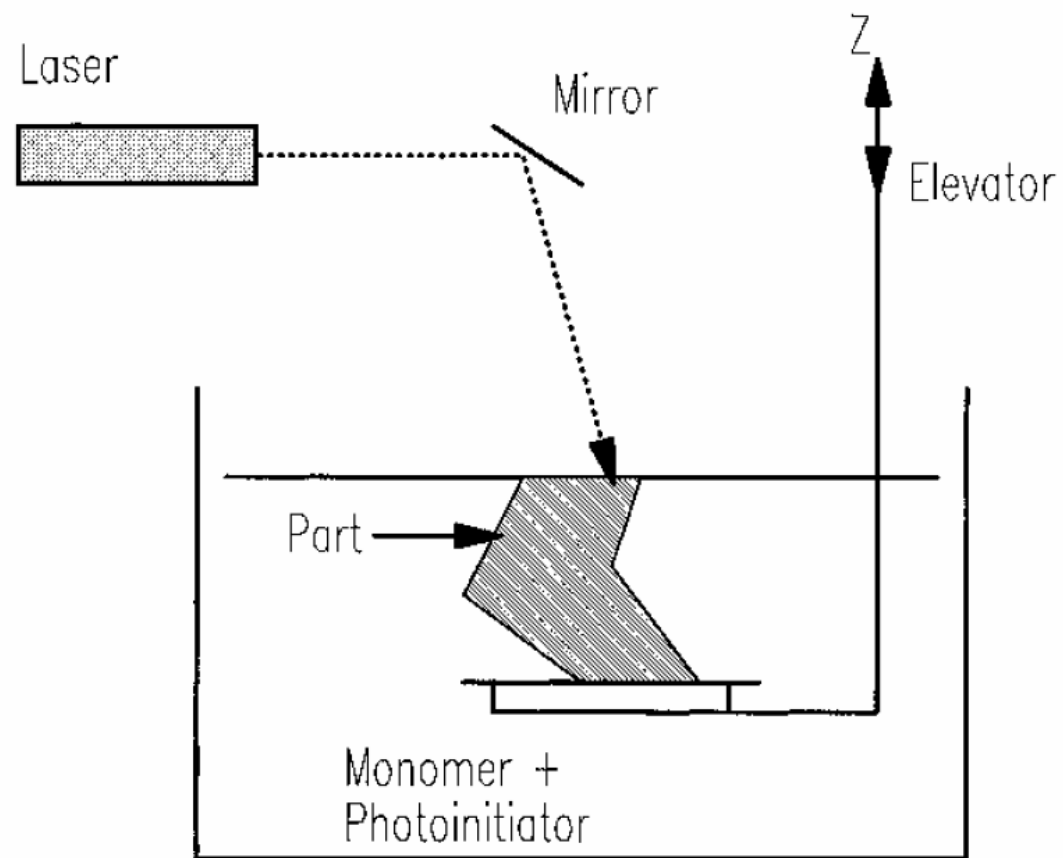
Fused deposition modeling

3D printing

and others

Most do one material at a time

Most do parts with low strength

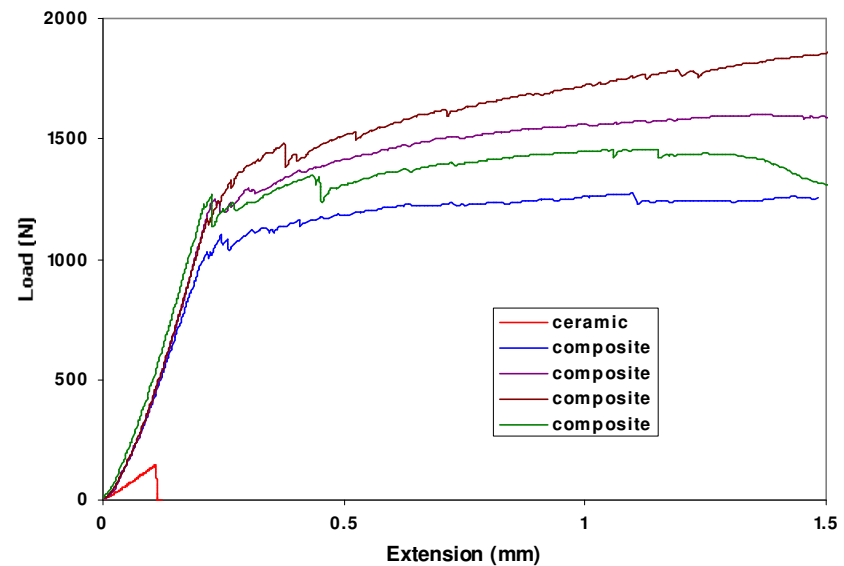
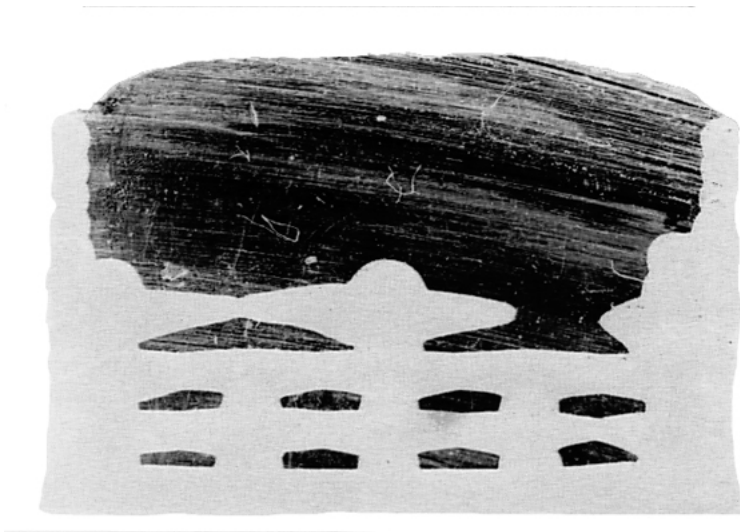


Stereolithography

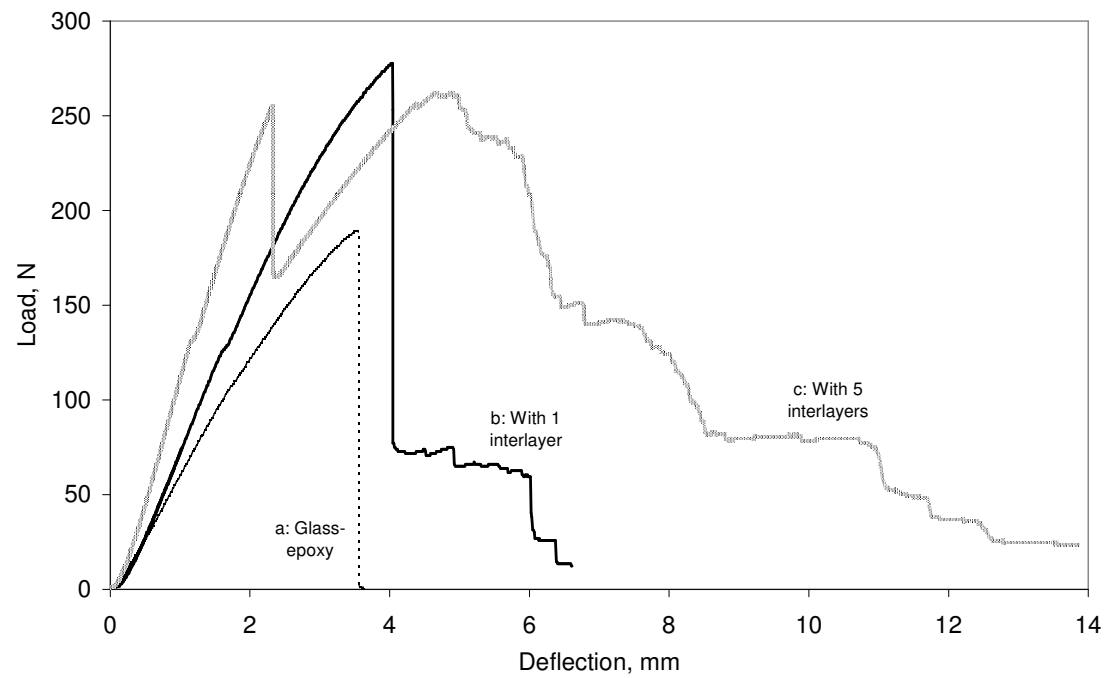
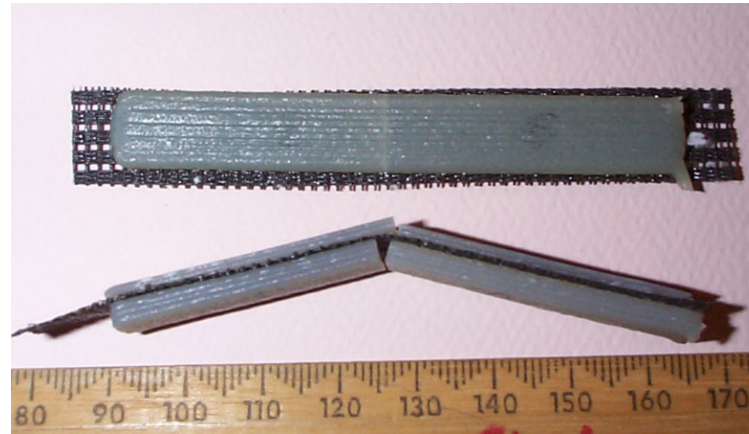


The image shows an Asymtek Automatic 400 Dispensing System. The control panel at the top includes several analog gauges for pressure and flow, a digital display showing '0.00', and various control buttons and switches. The dispensing head is mounted on a vertical rail and is positioned over a flat work surface. The machine is supported by two vertical legs.

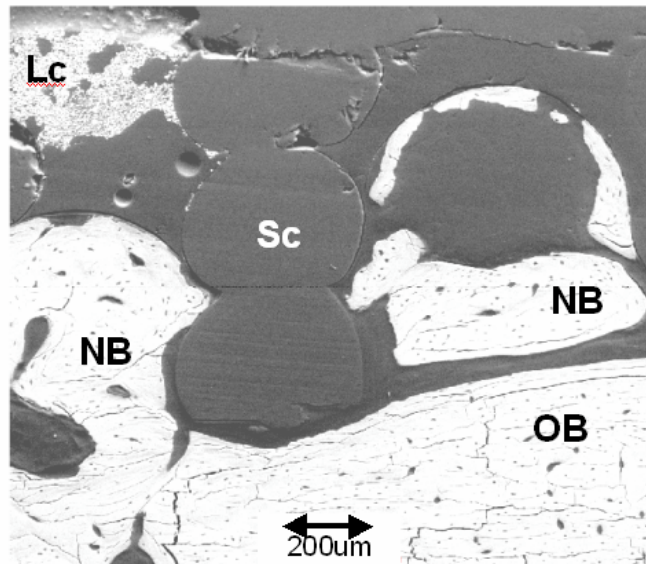
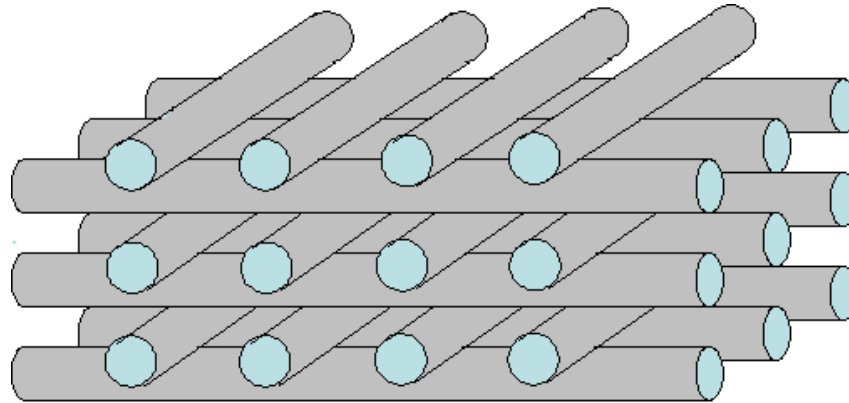
Cross-section of metal-ceramic composite fabricated by Robocasting of alumina ceramic followed by subsequent aluminum metal infiltration, contrast of the ceramic region altered. The metal phase is seen to wet the ceramic phase completely forming an interpenetrating structure. The resulting metal-ceramic combination is much tougher than pure ceramic.



Putting tough layers into epoxy composites enhances the toughness



Biodegradable “logpile” coated with tricalcium phosphate as a porous bone implant. Rat tests.



Environmental SEM of implant transverse section

OB – Old Bone

NB – New bone

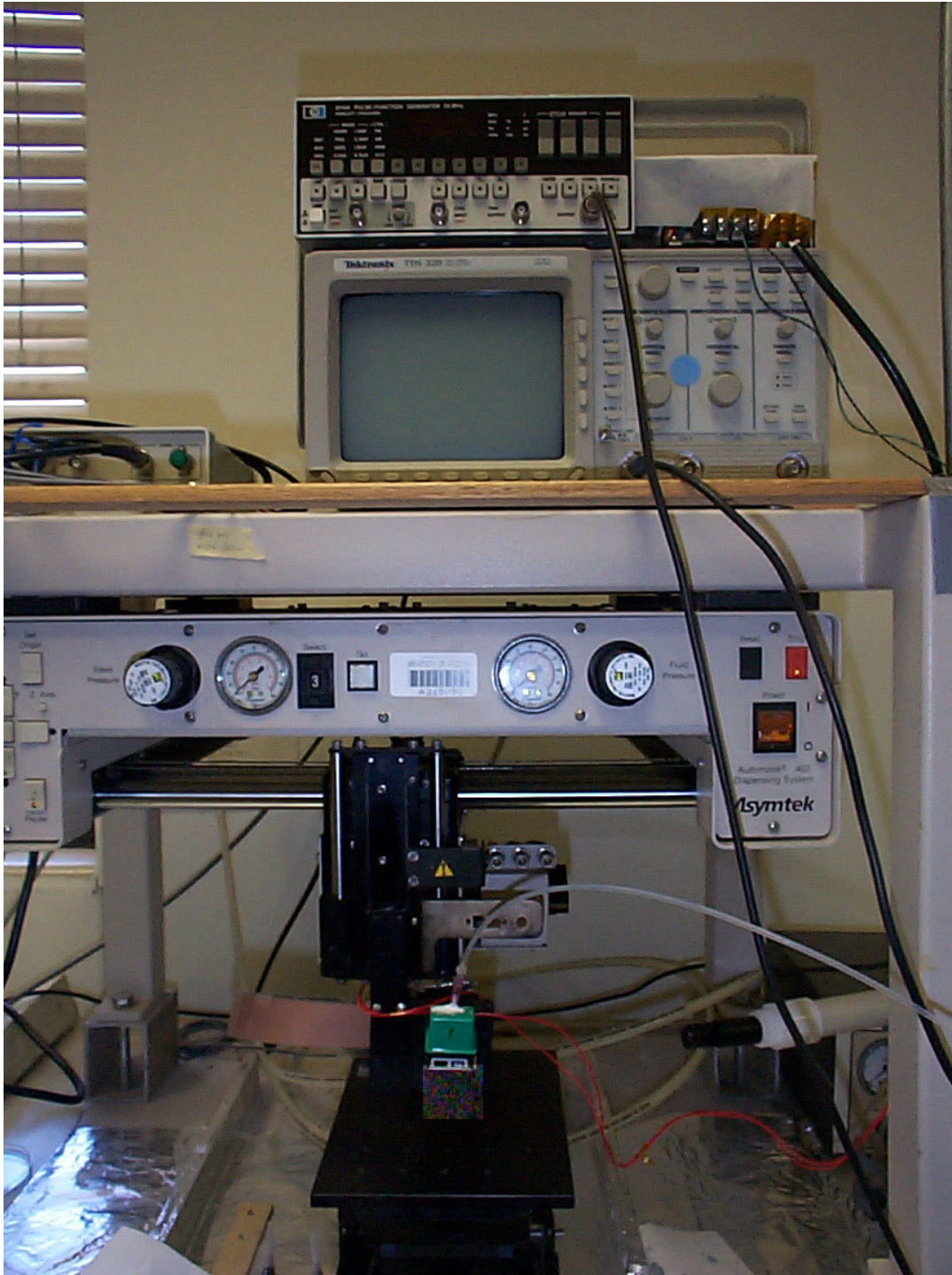
Sc – PBT Scaffold

Lc – PCL/TCP latex remnant

- Test coupon attached to femoral surface, allowed 4 months of ingrowth
- Bone ingrowth into pores clearly evident
- Osteons, haversian canals visible in NB

Inkjet printing for higher resolution

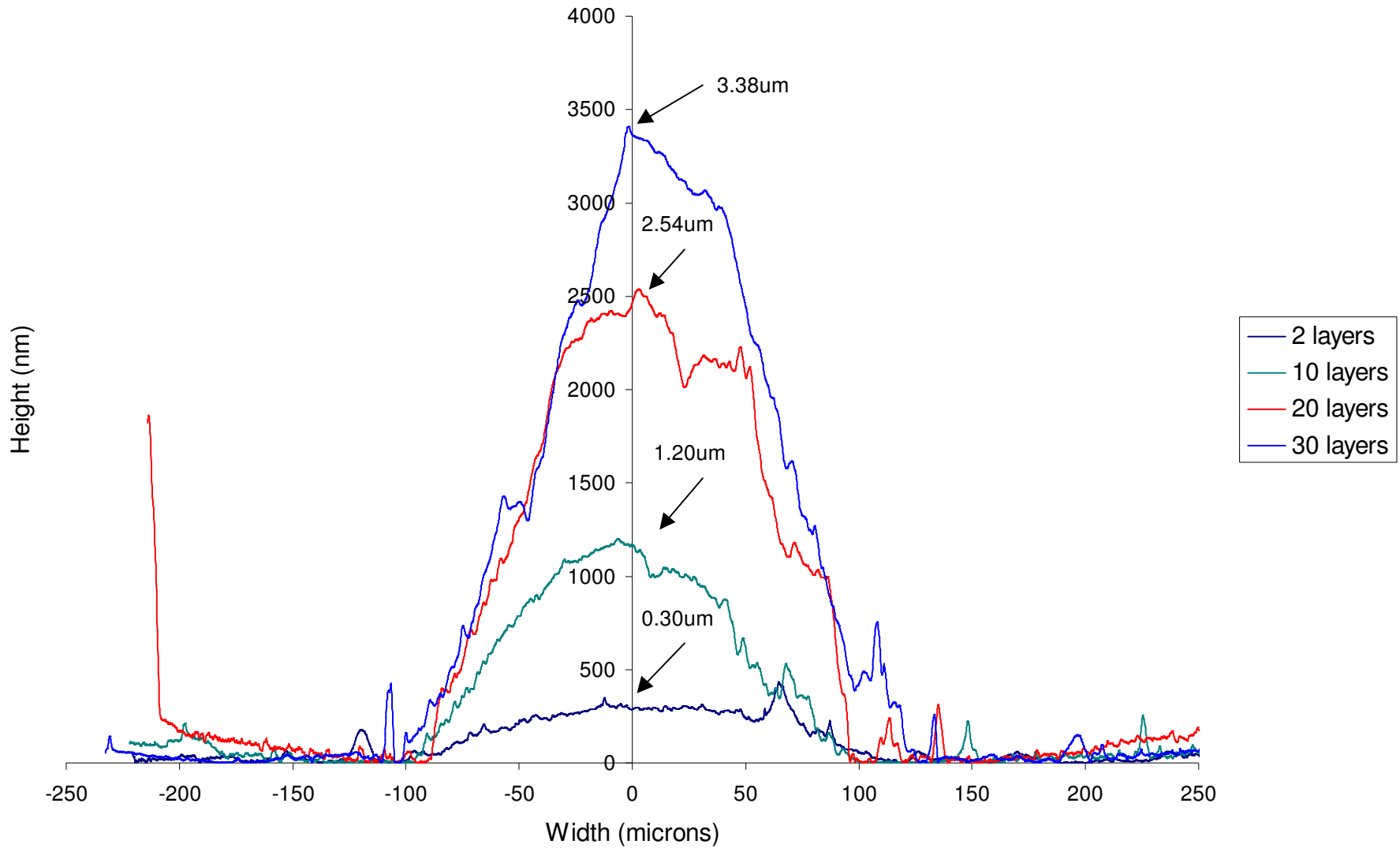
Printing PEDOT transparent conductors for OLEDs



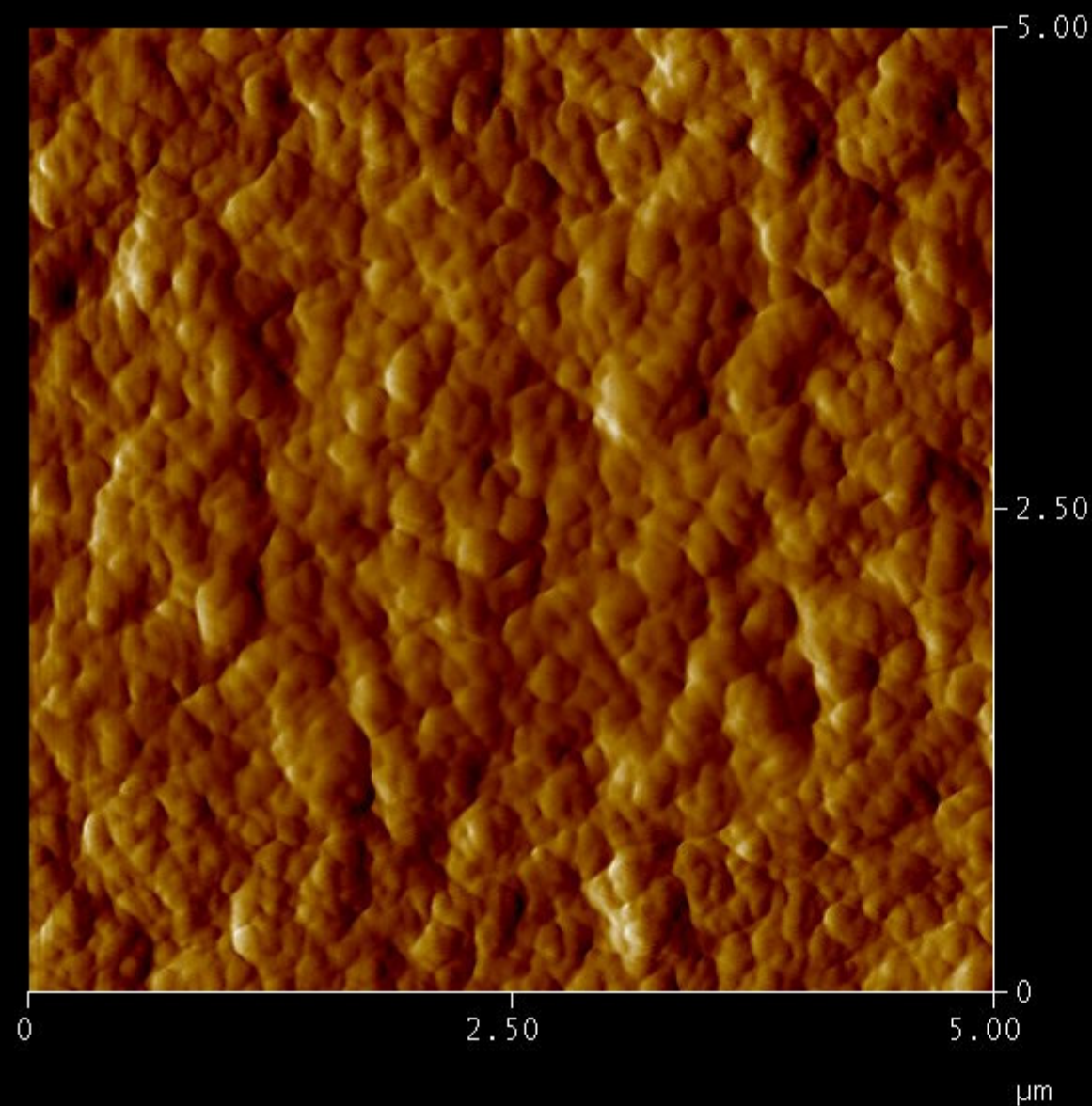
Pulse generator drives home-made current source, pulse a single nozzle.

Controlled vacuum prevents dripping

Surface profiles by Alfa-Step 500, Tencor, PEDOT lines 40 Hz



Overprinting a single line. Width does not change.
Resistivity $10^{-2} \Omega.m$

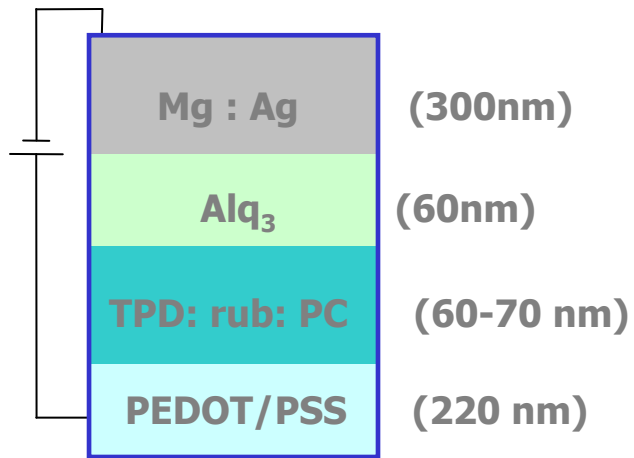


Digital Instruments NanoScope
Scan size 5.000 μm
Scan rate 10.99 Hz
Number of samples 512
Image Data Deflection
Data scale 11.00 nm

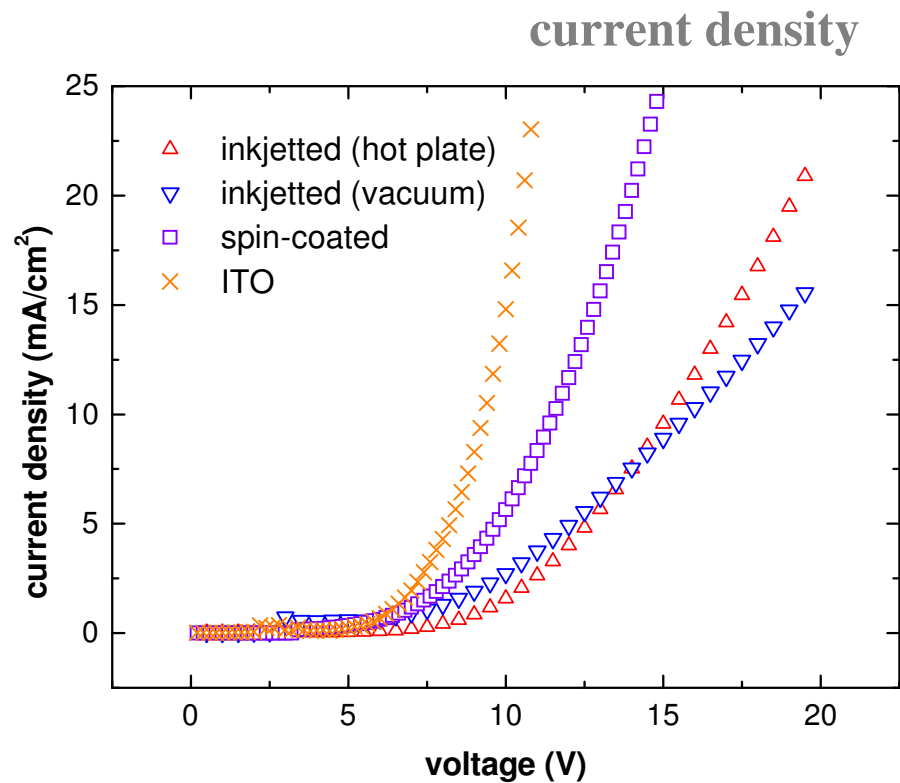
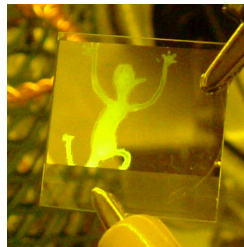
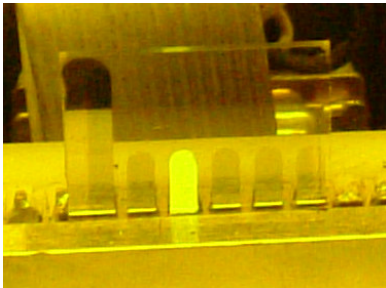
PDT 41, RMS 1.107nm

yypbt.004

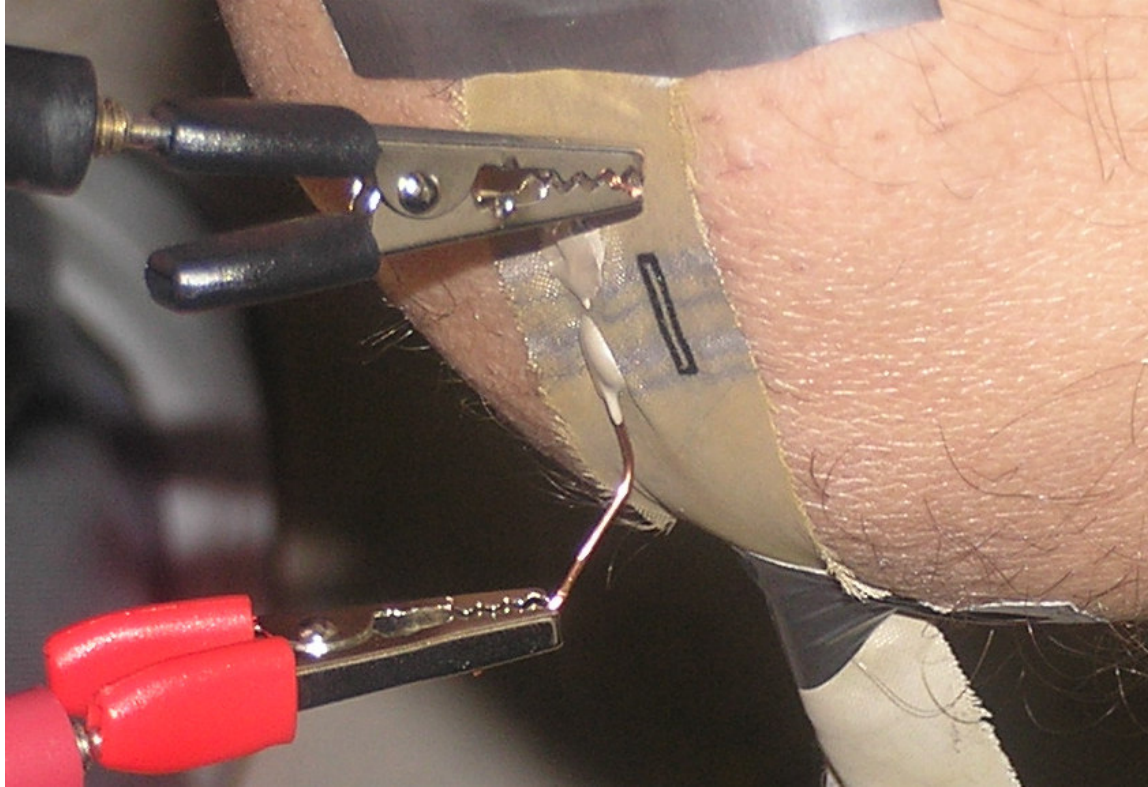
OLED characteristics



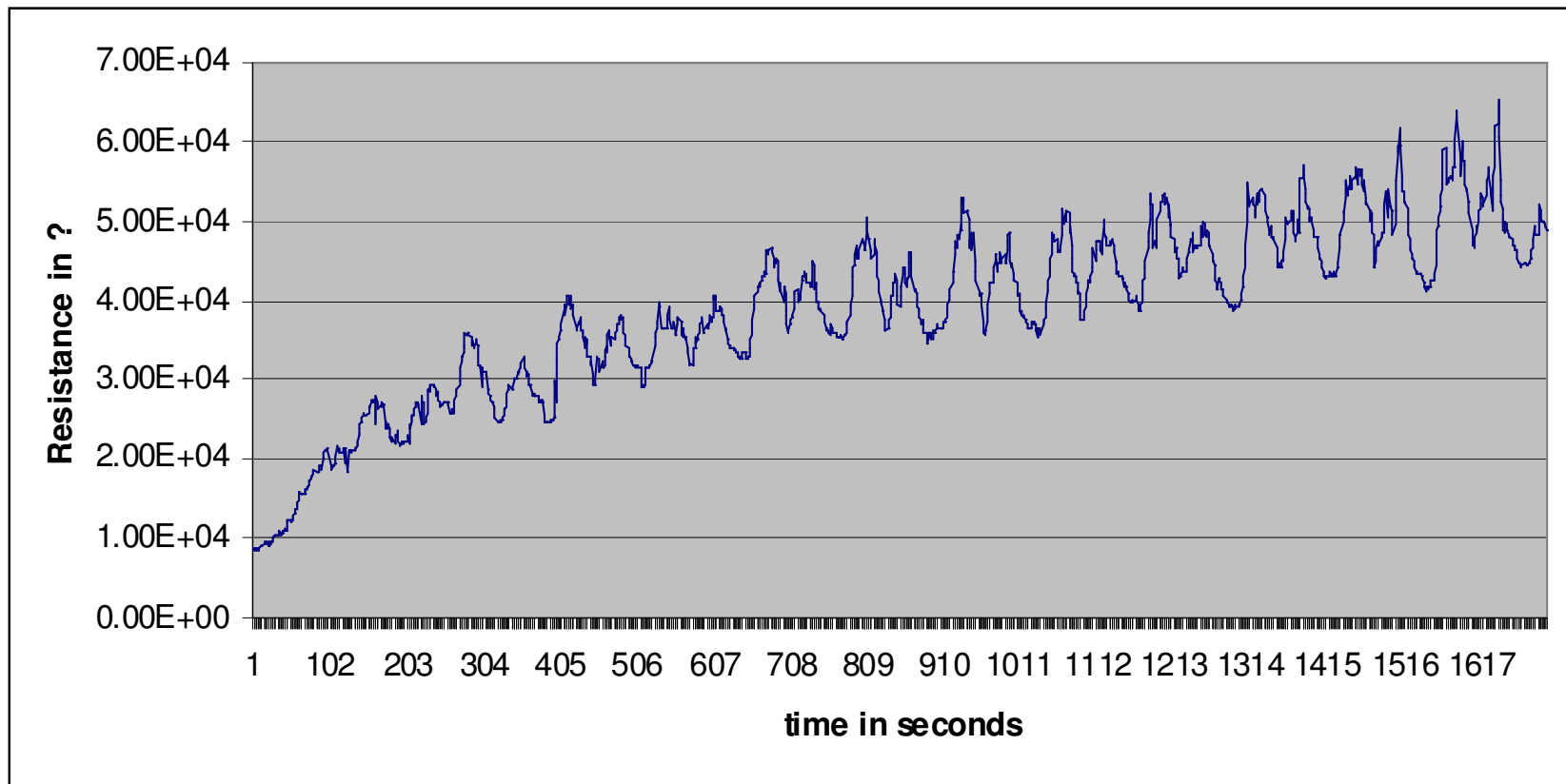
surface resistivity = 1800 Ω /sq.
conductivity = 25 S/cm



Printing strain sensors and chemical sensors onto textiles



Strain sensor on a knee

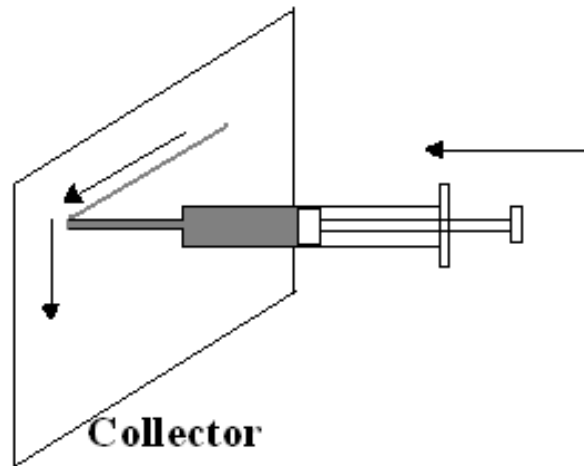


Variation in Resistance of PEDOT-PSS coated fabrics vs time within 25 repeated cycles of 5% strain and relaxation

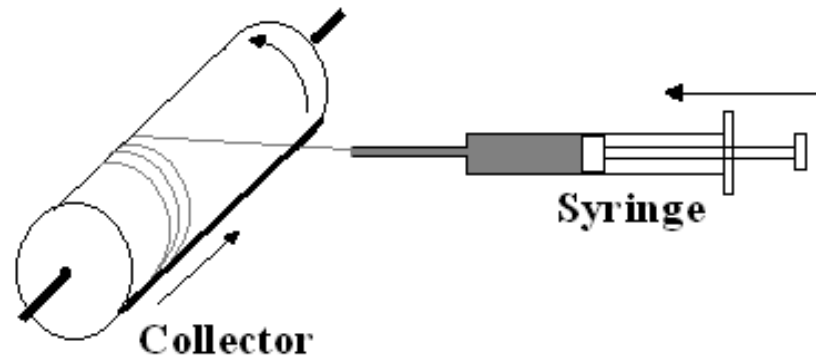
The Robospider

Develop methods to deposit fibers from small amounts of solution of valuable polymers, for electronic or biomedical applications.

Fibers can be written onto a surface or pulled onto a drum

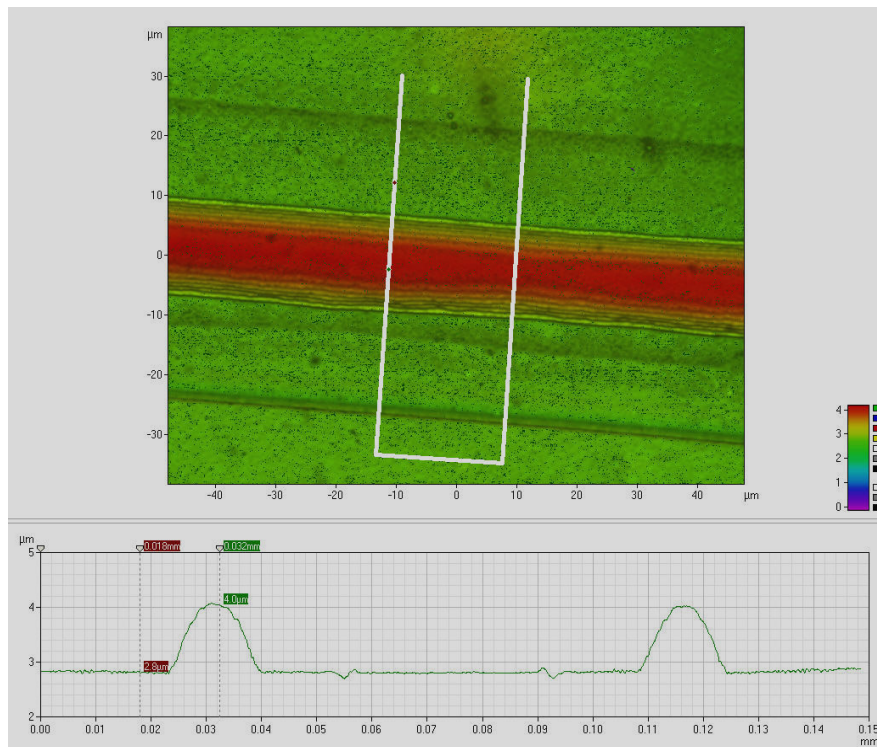


Method 1

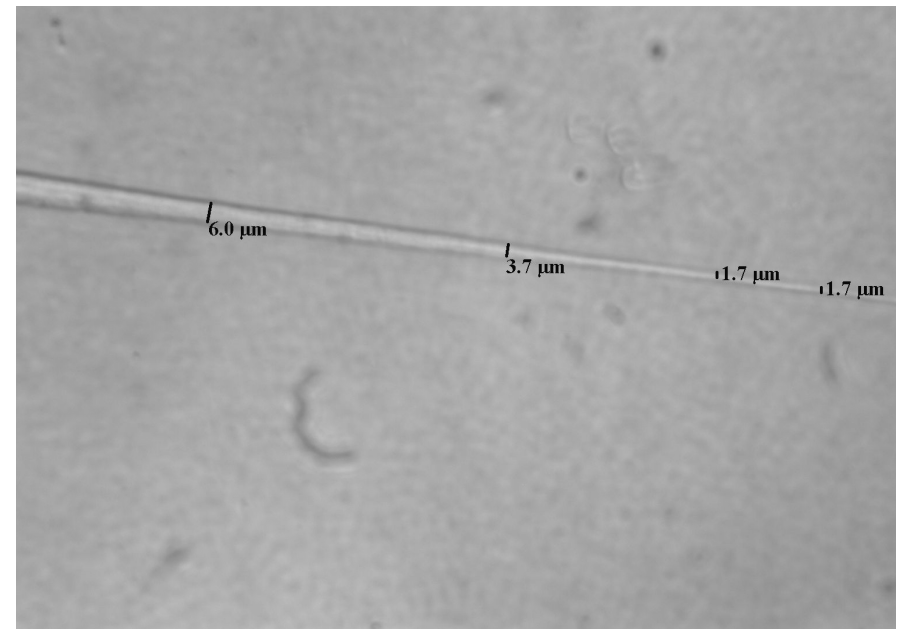


Method 2

Fiber written onto glass
100 microns wide, 1 micron high



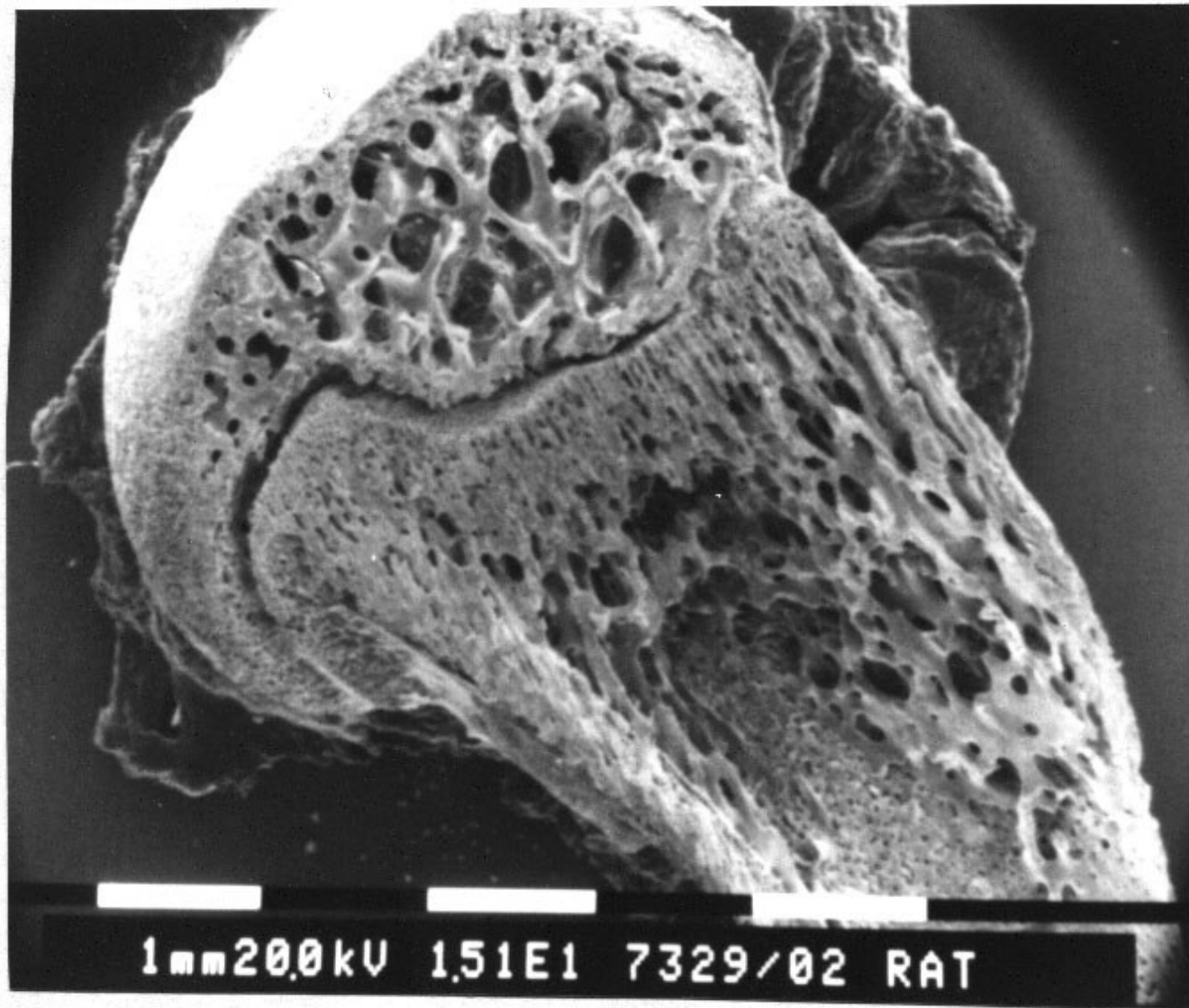
2 micron pulled fiber



Put all these methods together to write
fibers, resins, gels, conductors and devices
into a single system.

This is what happens during biological growth

Rat Bone with Growth Plate

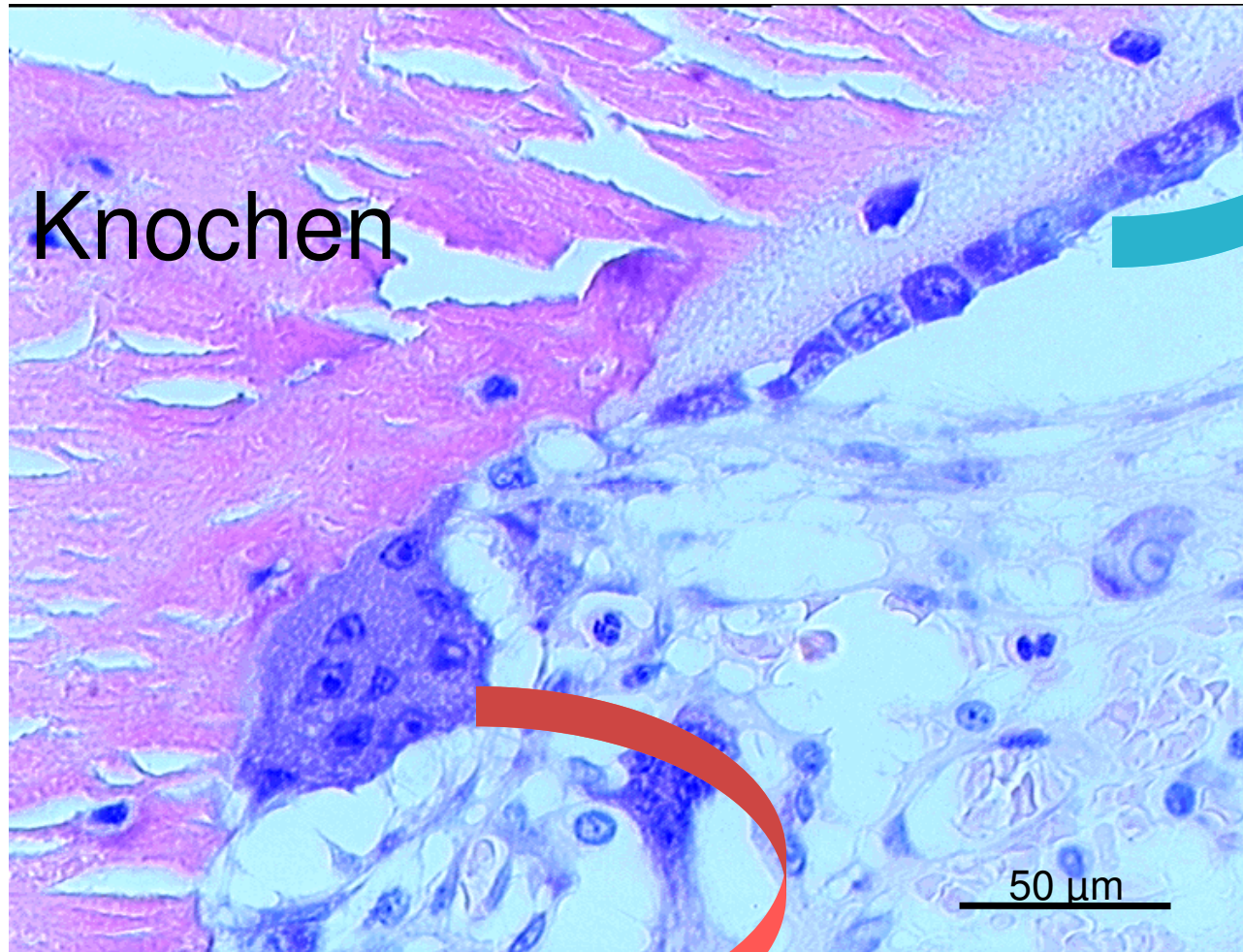


Bone cells

(Light microscopy, Giemsa)

formation

Osteoblasts



resorption

Osteoclasts

These robotic methods cannot compete for speed with conventional molding
They do compete with metal machining

and:

the parts are customizable

the equipment can be small

the functionality of the parts can be high

Thanks for support to:

National Textile Center, NIH, ICI Plc,

DoD for equipment